J is thus the determinant of the Jacobian of the transformation, or the "functional determinant."

The strain, N_{jk} , is defined, somewhat arbitrarily, from the difference in the squares of the lengths of line elements by:

$$2N_{jk} da_{j} da_{k} = dx_{i} dx_{i} - da_{i} da_{i}$$
$$N_{jk} = 1/2 \left(\frac{\partial x_{i}}{\partial a_{i}} \frac{\partial x_{i}}{\partial a_{k}} - \delta_{jk}\right)$$

Here and in the following the Einstein summation convention for repeated subscripts applies. δ_{ik} is the Kronecker delta.

Expanding the internal (strain) energy in a power series in the strains, one obtains (at constant entropy):

$$\rho_{0}[E(N,S) - E(0,S)] = 1/2 c_{ijkl}^{S} N_{ij} N_{kl} + 1/6 c_{ijklmn} N_{ij} N_{kl} N_{mn} + 1/24 c_{ijklmnpq}^{S} N_{ij} N_{kl} N_{mn} N_{pq} + ...$$
(2.16)

In this expression the c_{ijk}^s . . . , represent the second and higher order isentropic elastic stiffness coefficients. The first-order term is missing since the reference state is considered to be one of zero stress and strain.

We now define quantities, called thermodynamic tensions, by

$$t_{ij} = \rho_0(\frac{\partial E}{\partial N_{ij}}) \qquad (2.17)$$

(2.15)

In terms of these quantities the elastic constants are

 $c_{ijkl}^{s} = \left(\frac{\partial t_{ij}}{\partial N_{kl}}\right)_{s} = \frac{\partial^{2}E}{\partial N_{ij} \partial N_{kl}}$

and similarly for the higher order coefficients. Consequently,

$$\rho_0 dE = t_{ij} dN_{ij} (dS = 0)$$

Finally, the equilibrium (non-dissipative) components of the stress are obtained from the thermodynamic tensions by the relations,

$$\sigma_{x,\eta}^{-(1/j)} \frac{\partial x_k}{\partial a_j} \frac{\partial x_m}{\partial a_j} t_{ij}$$
 (2.18)

The above formulas provide isentropic constitutive relations in terms of the elastic stiffness coefficients. Other forms of constitutive relations can, of course, be derived in a similar fashion.

Low pressure acoustic measurements yield a mixed third-order constant of the form:

$$C_{ijkmpq} = \left(\frac{\partial C_{ijkm}}{\partial N_{pq}}\right)_{T}$$

where the subscript T means the derivative is taken at constant temperature. The corresponding purely isentropic constant is given by:

 $c_{ijkmpq}^{s} = C_{ijkmpq} + (T/\rho_{o} C_{t}) c_{kmpq}^{s} \alpha_{uv} [C_{ijkmrs} \alpha_{rs} - (\frac{\partial c_{ijkm}^{s}}{\partial T})_{t}]$ (2.19)

where $C_{\rm t}$ is the specific heat at constant tension and the $\alpha_{\rm uv}$ are thermal expansion coefficients,

$$x_{uv} = \left(\frac{\partial N_{uv}}{\partial T}\right)_t$$

In view of the symmetry of the stress and strain tensors, the number of subscripts can be reduced by adopting the following convention:

 $11 \rightarrow 1$ $32 \rightarrow 4$ $22 \rightarrow 2$ $31 \rightarrow 5$ $33 \rightarrow 3$ $21 \rightarrow 6$

This convention is employed in the following.